Limited Information Strategies in Star Selection Games

Jared Holshouser (with Chris Caruvana)

Mathematics Department Norwich University

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Selection Principles (Menger, Hurewicz 1924) (Scheepers 1996)

Suppose that \mathcal{A} and \mathcal{B} are collections.

$S_1(\mathcal{A},\mathcal{B})$

 $S_1(\mathcal{A}, \mathcal{B})$ means that for all sequences A_n consisting of elements of \mathcal{A} , there are choices $x_n \in A_n$ so that $\{x_n : n \in \omega\} \in \mathcal{B}$.

$S_{\text{fin}}(\mathcal{A},\mathcal{B})$

 $S_{\text{fin}}(\mathcal{A}, \mathcal{B})$ means that for all sequences A_n consisting of elements of \mathcal{A} , there are finite $F_n \subseteq A_n$ so that $\bigcup_n F_n \in \mathcal{B}$.

Let $\mathcal{O}(X)$ denote the open covers of X. A basic example of a selection principle is $S_1(\mathcal{O}(X), \mathcal{O}(X))$, a generalization of compactness that we refer to as **Rothberger**.

- We can view the selection principle $S_1(\mathcal{A}, \mathcal{B})$ as a game process wherein player I plays sets A_n and player II responds with $x_n \in A_n$.
- Player II wins if $\{x_n : n \in \omega\} \in \mathcal{B}$. We call this game $G_1(\mathcal{A}, \mathcal{B})$. Otherwise player I wins.
- In this game framework it's natural to impose information conditions on the players. These create a hierarchy of statements. In the Rothberger case, this looks like

 $X \text{ is ctbl } \to \text{ II wins } G_1(\mathcal{O}, \mathcal{O}) \to \text{ I doesn't win } G_1(\mathcal{O}, \mathcal{O}) \to S_1(\mathcal{O}, \mathcal{O})$

Definition

Define $G_1(\mathcal{A}, \mathcal{C}) \leq_{\mathrm{II}} G_1(\mathcal{B}, \mathcal{D})$ as the conjunction of the following implications.

- Two has a strategy for $G_1(\mathcal{A}, \mathcal{C}) \implies$ Two has a strategy of the same level for $G_1(\mathcal{B}, \mathcal{D})$.
- **2** One does not have a strategy for $G_1(\mathcal{A}, \mathcal{C}) \implies$ One does not have a strategy at that same level for $G_1(\mathcal{B}, \mathcal{D})$.
 - This relation is transitive.
 - There is a fin version of all of this.

General Translation

If we can build the picture below, then $G_1(\mathcal{A}, \mathcal{C}) \leq_{\mathrm{II}} G_1(\mathcal{B}, \mathcal{D})$.



There is a small modification of this that works simultaneously for G_1 and G_{fin} .

ω -Covers

A non-trivial open cover \mathscr{U} of X is an ω -cover if for each finite $F \subseteq X$, there is a $U \in \mathscr{U}$ so that $F \subseteq U$. We use $\Omega(X)$ to refer to the collection of ω -covers.



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Stars

If \mathscr{U} is an open cover of X and $A \subseteq X$, then $\operatorname{St}(A, \mathscr{U}) = \bigcup \{ U \in \mathscr{U} : U \cap A \neq \emptyset \}.$

Star Selections (Kocinac, 1999)

- The symbol $S_1^*(\mathcal{O}, \mathcal{B})$ says that for each sequence of open covers \mathscr{U}_n , there are open sets $U_n \in \mathscr{U}_n$ so that $\{\operatorname{St}(U_n, \mathscr{U}_n) : n \in \omega\} \in \mathcal{B}$.
- The symbol $SS^*_{\mathcal{A}}(\mathcal{O}, \mathcal{B})$ says for each sequence of open covers \mathscr{U}_n , there is a sequence of $A_n \in \mathcal{A}$ so that $\{St(A_n, \mathscr{U}_n) : n \in \omega\} \in \mathcal{B}.$

Star covering properties appeared at least as early as 1991 (E.K. van Douwen, G.M. Reed, A.W. Roscoe and I.J. Tree).

Star Selection Principles are Selection Principles

Constellations and Galaxies

- If \mathscr{U} is an open cover of X and \mathcal{A} is a collection of subsets of X, then $\operatorname{Cons}(\mathcal{A}, \mathscr{U}) = {\operatorname{St}(\mathcal{A}, \mathscr{U}) : \mathcal{A} \in \mathcal{A}}.$
- If \mathscr{C} is a collection of open covers of X and $f : \mathscr{C} \to \mathcal{P}(\mathcal{P}(X))$, then $\operatorname{Gal}(f, \mathscr{C}) = \{ \operatorname{Cons}(f(\mathscr{U}), \mathscr{U}) : \mathscr{U} \in \mathscr{C} \}.$

Star Selections

- $S_1^*(\mathcal{O}, \mathcal{B})$ is equivalent to $S_1(\text{Gal}(\text{id}, \mathcal{O}), \mathcal{B})$.
- $SS^*_{\mathcal{A}}(\mathcal{O},\mathcal{B})$ is equivalent to $S_1(\operatorname{Gal}(\mathcal{A},\mathcal{O}),\mathcal{B})$.

With this equivalence in mind, we will reference the corresponding games $G_1^*(\mathcal{O}, \mathcal{B})$ and $SG_1^*(\mathcal{O}, \mathcal{B})$ and note that the translation theorem can be applied to it.

Definition (Pixley and Roy, 1969)

We define the topological space PR(X) as follows:

- points in PR(X) are finite subsets of X, and
- A basic open set has the from $[F, U] = \{G \subseteq X : F \subseteq G \subseteq U\}$, where F and G are finite and U is open in X.

This topology is finer than the Fell topology and was initially created as an interesting space for counter-examples.

Theorem (Sakai, 2014)

Suppose X is regular. Then $S^*_{\Box}(\mathcal{O}(\mathrm{PR}(X)), \mathcal{O}(\mathrm{PR}(X))) \implies S_{\Box}(\Omega(X), \Omega(X)).$

We boost this up to the following result.

Theorem (Caruvana and Holshouser, 2022)

Assume X is regular. Then $G^*_{\Box}(\mathcal{O}(\mathrm{PR}(X)), \mathcal{O}(\mathrm{PR}(X))) \leq_{\mathrm{II}} G_{\Box}(\Omega(X), \Omega(X)).$



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$G^*_{\Box}(\mathcal{O}(\mathrm{PR}(X)), \mathcal{O}(\mathrm{PR}(X))) \leq_{\mathrm{II}} G_{\Box}(\Omega(X), \Omega(X))$





Limited Information Strategies in Star Selection Games 16 $G^*_{\Box}(\mathcal{O}(\operatorname{PR}(X)), \mathcal{O}(\operatorname{PR}(X))) \leq_{\operatorname{II}} G_{\Box}(\Omega(X), \Omega(X))$

Theorem (Caruvana and Holshouser 2022)

There is a version of the translation theorem where $\overleftarrow{T}_{I,n}$ doesn't have to pick out an individual from \mathcal{A} , but instead it picks out a subset of \mathcal{A} .



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Star Selection in Uniform Spaces

Definition

Given a uniform space (X, \mathcal{E}) and a collection \mathscr{U} of subsets of X, \mathscr{U} is a **uniform cover** of X (with respect to \mathcal{E}) if there exists $E \in \mathcal{E}$ so that $\{E[x] : x \in X\}$ is a refinement of \mathscr{U} .

We will say a uniform cover is an **open uniform cover** if it consists of open sets.

Let $\mathcal{C}_{\mathcal{E}}(X)$ be the collection of all open uniform covers with respect to \mathcal{E} .

Theorem (Caruvana and Holshouser, 2022)

Let (X, \mathcal{E}) be a uniform space. Then

$$\mathsf{G}_{\Box}(\mathcal{C}_{\mathcal{E}}(X),\mathcal{O}_X) \equiv \mathsf{S}\mathsf{G}^*_{X,\Box}(\mathcal{C}_{\mathcal{E}}(X),\mathcal{O}_X) \equiv \mathsf{G}^*_{\Box}(\mathcal{C}_{\mathcal{E}}(X),\mathcal{O}_X).$$

This theorem extends a result of Kocinac (2003).

 $\mathsf{G}_{\Box}(\mathcal{C}_{\mathcal{E}}(X),\mathcal{O}_X) \leq_{\mathrm{II}} \mathsf{SG}^*_{X,\Box}(\mathcal{C}_{\mathcal{E}}(X),\mathcal{O}_X)$



- $\mathscr{U} \sim_E \mathscr{V}$ means $\operatorname{Cons}(X, \mathscr{U}) = \operatorname{Cons}(X, \mathscr{V}).$
- For each open $V \in \mathscr{T}_X$, choose $x_V \in V$.
- Check that if $V_n \in \mathscr{V}_n \in [\mathscr{U}_n]_E$, then $\operatorname{St}(x_{V_n}, \mathscr{V}_n) \in \operatorname{Cons}(X, \mathscr{U}_n)$.
- Check that if $X = \bigcup_n V_n$, then $X = \bigcup_n \operatorname{St}(x_{V_n}, \mathscr{V}_n)$.



Thanks for Listening



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